



About map data

Back in the day

... a static local map in the vehicle was state of the art

... which was updated first once a year, then two times, then four times per year

Today

... dynamic and up-to-date map data is needed to serve ADAS/AD

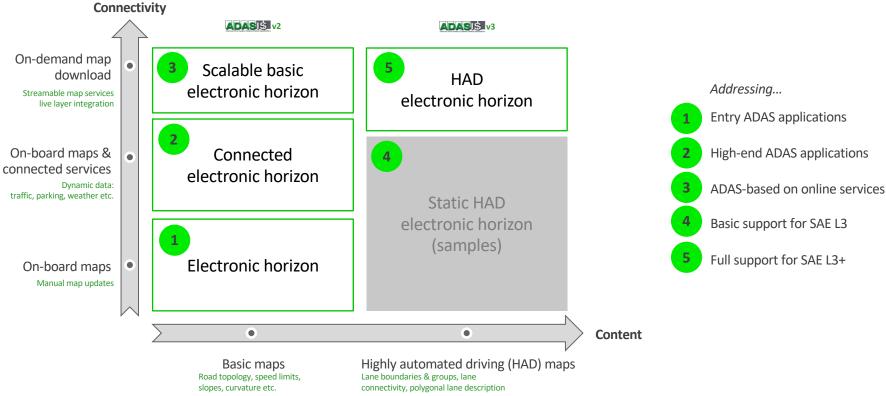
... systems with an HD map have the need of a streamable map

... even systems which use an SD map ask for streamable solutions



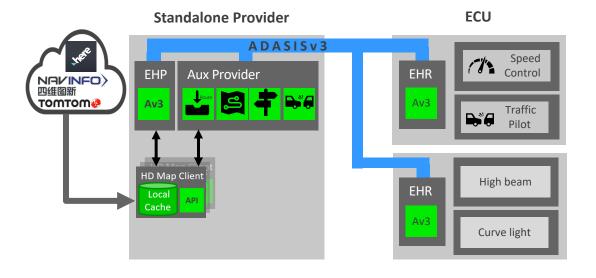


EB robinos Provider





Status Quo today



Protocol compatibility

- Fully compliant to the current ADASIS v3 standard
- Easy extendable though custom profiles

HD MAP

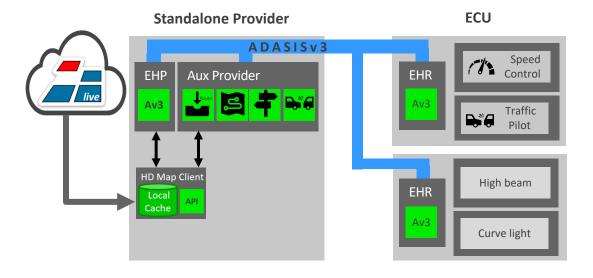
- Latest map updates through OTA connection
- Intelligent caching mechanism to avoid unnecessary data traffic
- Abstract backed architecture to be technology- and map-provider-independent

Dvnamic data

- Auxiliary provider enables possibility to extend the ADASISv3 stream with dynamic information:
 - Traffic incidents
 - Weather
 - Car2X data



Setup with NDS.Live



Protocol compatibility

 ADASIS compatibility is still given due to clear map abstraction concepts

HD MAP

- Architecture changes from supporting multiple APIs to NDS.Live
- Only one NDS.Live Map Client implementation needed
- Caching strategies are available and can be reused
- Abstract backed architecture to be technology and map provider independent

Dynamic data

- Auxiliary data can now also be handled through the same interfaces
- Auxiliary provider can facilitate the availability of data layers in NDS.Live



Changes needed for NDS.Live

Integration of NDS.Live access components

- ::nds::registry::services::client
- ::nds::smart::services::client
- ::nds::smart::tile::SmartLayerTile

Implementation changes to new data structures

- NDSLive_map_client to connect to the service api by using the ::nds::registry::services::client
- Fetch map via the nds::smart::services::Client and the corresponding TileId to populate the local cache
- Adapt the map abstractor to NDS.Live data structures
- Build up the ADASIS v3 tree

nds::smart::services::Client - m_service:::zserio::IService& + getLayerByTileIdMethod(const ::std::vector<uint8_t>&, ::std::vector<uint8_t>&, void*): void + getServiceCapabilitiesMethod(const ::std::vector<uint8_t>&, ::std::vector<uint8_t>&, void*): void + getServiceDefinitionMethod(const ::std::vector<uint8_t>&, ::std::vector<uint8_t>&, void*): void + getServiceNodeSystemReferenceMethod(const ::std::vector<uint8_t>&, ::std::vector<uint8_t>&, ::std::vector<uint8_t>&, void*): void

::nds::smart::tile::SmartLayerTile

m_header_j::nds::smart.types::SmartLayerHeader
m_layers_j::std::wectors:inds::smartLayerDataLayer>
m_tileld_i::nds::core:basics:packedTileld

::nds::registry::services::NdsRegistry::Client

- m_service::zserio::Service&

+ add_service_connector(:zserio::Service&): void

+ getAllNodesMethod(:nds::system::types::NdsSystemToken&, :nds::registry::node::NodeList&): void

+ getSystemMetadataMethod(:nds::system::types::NdsSystemToken&, :nds::registry::netadata::SystemMetadata&): void

+ registerNodeMethod(:nds::registry::node::NdsSystemToken&, :nds::registry::node::NodeList&): void

+ searchNodesMethod(:nds::registry::node::NdsNodeToken&, :nds::registry::node::NodeList&): void

+ unregisterNodeMethod(:nds::registry::node::NdsNodeToken&, :nds::core::basics::Empty&): void



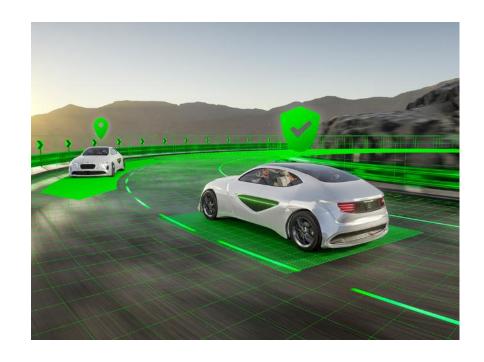
Possible use cases covered with NDS.Live

ADASIS v2 (road-based)

- Intelligent Speed Assist
- Enrich database with additional data from different sources.

ADASIS v3 (lane-based)

- Dynamically download additional map data to support the update of ADAS features via OTA software update
- Download more map layers as they become available by the map provider
- Download local object maps on demand (truck hubs, parking garages, company campus)





What's next?

Adding support for

- · ... ADASIS v2 based on NDS.Live
- ... map streaming by path and object
- both road- and lane-based map materials
- additional attribute coverage (e.g. truck attributes)





Demo video / live demo

